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is awarded to

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in recognition of valuable contribution as

Paper Presenter

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September 5-7 2018, Yogyakarta, Indonesia


Ali Awaludin
Chair

CONFERENCE GENERAL INFORMATION

Title of the conference : International Conference on Sustainable Civil Engineering Structures and Construction Materials (SCESCM) 2018

Date of the conference : September 5-7, 2018

Location of the conference : Royal Ambarrukmo Hotel, Yogyakarta, Indonesia

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Welcoming Remarks

from The 4th SCESCM Chair

Dear participants,

It is my great pleasure to welcome you in The 4th SCESCM here at Royal Ambarukmo Hotel, Yogyakarta, Indonesia.

I would like to express my appreciation to all the co-organizers institutes, universities from Indonesia and universities outside the country. Also to the all the third parties, PT. Pamapersada Nusantara, PT. Adhi Karya, PT. Inti Beton, PT. Cigading Habeam Centre, PT. Geofroce Indonesia, PT. Wika Beton, PT. Hutama Karya, PT PP, PT. Waskita Karya, PT. Tamara Overseas, PT. Fyfe Fibrwrap, PT. Jasamarga Japek Selatan, and PT. Semen Indonesia who provide financial support for us, to Indonesian Society of Civil and Structural Engineers, Asian Concrete Federation, Japan Society of Civil Engineers, International Federation for Structural Concrete, the International Association for Bridge and Structural Engineering as supporting institutions, and to all the reviewers who have worked on their best helping us to sort hundreds of papers from around the world.

To gather and to share all knowledge and research results from students, academicians and professionals, in 2012 the first SCESCM conference was organized focusing on sustainability concept implemented in design, construction and maintenance in any civil engineering structure. Since then, the conference is organized biannually and is increasingly enriched by outstanding keynotes, invited papers and selected participant's papers sharing the latest scientific findings and achievements among civil engineers across the globe.

This time, SCESCM received 129 technical papers from various country and will be published in MATEC WEB Conference which is indexed by Scopus.

We really hope this 4th SCESCM under the theme “Sustainable Structures for Future Generation” will provide us a valuable opportunity to share knowledges and experiences. SCESCM has also been introducing local cultures of Indonesia at the welcome dinner and optional cultural tour on a day after the conference. Once again, welcome to The 4th SCESCM ! We wish you a productive conference, and hope you enjoy your time here in Yogyakarta. Thank you.

Ali Awaludin, Ph.D.

Chair



[All issues](#) ▶ Volume 258 (2019)

[◀ Previous issue](#)

[Table of Contents](#)

[Next issue ▶](#)

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MATEC Web of Conferences

Volume 258 (2019)

International Conference on Sustainable Civil Engineering Structures and Construction Materials (SCESCM 2018)

Yogyakarta, Indonesia, September 5-7, 2018

A. Awaludin, T. Matsumoto, S. Pessiki, H. Jonkers, S. Siswosukarto, A. Fajar Setiawan and K. Nur Rahma Putri
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- ✓ [Hybrid and Composite Structures, Smart Materials and Structures, Special Structures](#)
- ✓ [Structural Dynamics and Earthquake Engineering, Structures in Severe Environment, Structural Analysis](#)

- Green Construction Materials and Technologies, Environmental Impact and Green Design, Local and Recycled Materials

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Sustainable cementitious materials: The effect of fly ash percentage as a part replacement of portland cement composite (PCC) and curing temperature on the early age strength of fly ash concrete 01001

Gidion Turuallo and Harun Mallisa

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[PDF \(1.451 MB\)](#) | [References](#)

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The effect of density and height of vegetation in open channel on the Manning's coefficient 01002

Maimun Rizalihadi

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DOI: <https://doi.org/10.1051/mateconf/201925801002>

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The effect of laterite stone as filler on marshall stability hot mix asphalt AC-WC 01003

Istiar, Tri Joko Wahyu Adi, Sutikno, Rahmat, Martheana Kencanawati and Ilham Siara

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DOI: <https://doi.org/10.1051/mateconf/201925801003>

[PDF \(1.800 MB\)](#) | [References](#)

Open Access

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DOI: <https://doi.org/10.1051/matecconf/201925801004>

PDF (1.718 MB) | [References](#)

Open Access

The Influence of Rice Husk on the Physical Properties of Portland Pozzoland Cement at the Cement Industry Scale 01005

Agus Maryoto and Gathot Heri Sudibyo

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PDF (1.640 MB) | [References](#)

Open Access

The influence of the usage of Idpe plastic waste as fine aggregate in light concrete bricks 01006

Nursyamsi Nursyamsi, Ivan Indrawan and Prasetyo Ramadhan

Published online: 25 January 2019

DOI: <https://doi.org/10.1051/matecconf/201925801006>

PDF (1.759 MB) | [References](#)

Open Access

The pull-out test on knit bamboo reinforcement embedded into concrete beam 01007

Devi Nuralinah

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Open Access

The sustainability of public transport operation based on financial point of view 01008

Arif Budiarto

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PDF (1.911 MB) | [References](#)

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A mockup unit of the an-eco budget bamboo chalet: design and cost estimation analysis 01010

Hazrina Mansor, Nursuzila M. A. A. Wahab, Yazmin Sahol Hamid and Mohd Khairul Kamarudin

Published online: 25 January 2019

DOI: <https://doi.org/10.1051/matecconf/201925801010>

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A study into flexural, compressive and tensile strength of coir-concrete as sustainable building material 01011

Rilya Rumbayan, Sudarno and Adriana Ticoalu

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DOI: <https://doi.org/10.1051/matecconf/201925801011>

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Adhesion characteristics of geopolymer mortar to concrete and rebars 01012

Sanjay Pareek, Hiroo Kashima, Ippei Maruyama and Yoshikazu Araki

Published online: 25 January 2019

DOI: <https://doi.org/10.1051/matecconf/201925801012>

PDF (2.507 MB) | [References](#)

Open Access

Application of bio-based material for concrete repair: case study leakage on parallel concrete slab 01013

Prima Yane Putri, Isao Ujike and Keiyu Kawaai

Published online: 25 January 2019

DOI: <https://doi.org/10.1051/matecconf/201925801013>

PDF (2.262 MB) | [References](#)

(RHA) with hydrated lime as additive 01014

Noorfaizah Hamzah, Nur 'Ain Mat Yusof and Muhammad Ihsan Haziq Mohd Rahimi

Published online: 25 January 2019

DOI: <https://doi.org/10.1051/mateconf/201925801014>

PDF (2.011 MB) | [References](#)

Open Access

Concrete using sawdust as partial replacement of sand : Is it strong and does not endanger health? 01015

Nurul Huda Suliman, Amir Atif Abdul Razak, Hazrina Mansor, Anizahyati Alisibramulisi and Norliyati Mohd Amin

Published online: 25 January 2019

DOI: <https://doi.org/10.1051/mateconf/201925801015>

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Open Access

Construction cleared land impact on air quality deterioration: quantification of soil borne dustfall and suspended particulate generation 01016

Arief Sabdo Yuwono, Iskandar, Muhammad Fauzan, Elsy Gustika Buana, Agung Abdul Ra'up and Ety Herwati

Published online: 25 January 2019

DOI: <https://doi.org/10.1051/mateconf/201925801016>

PDF (1.978 MB) | [References](#)

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Design and FE Modeling of UPVC Corrugated Hollow Roofing Sheet 01017

Djoko Setyanto

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DOI: <https://doi.org/10.1051/mateconf/201925801017>

PDF (2.087 MB) | [References](#)

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Evaluation of Pervious Concrete Utilizing Recycled HDPE as Partial Replacement of Coarse Aggregate with Acrylic as Additive 01018

Neslyn Lopez, Emilia Collado, Lois Alexandra Diacos and Harold Dave Morente

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Fundamental factors on the behaviour of bagasse ash stabilized organic soil 01019

John Tri Hatmoko and Hendra Suryadharma

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Influence of polypropylene fiber on early strength of self-compacting concrete 01020

Rahmi Karolina and Abdiansyah Putra Siregar

Published online: 25 January 2019

DOI: <https://doi.org/10.1051/mateconf/201925801020>

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Phytoremediation of heavy metal from leachate using *imperata cylindrica* 01021

Khairul Anam Moktar and Ramlah Mohd Tajuddin

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DOI: <https://doi.org/10.1051/mateconf/201925801021>

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Preservation of durian timber and coconut timber with soursop leaf extract 01022

Sri Handayani, Endah Kanti Pangestuti and Ninda Adhitya Dharma

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DOI: <https://doi.org/10.1051/mateconf/201925801022>

PDF (1.803 MB) | [References](#)

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Review of creep modelling for predicting of long-term behavior of glued-laminated bamboo structures 01023

Ngudiyono, Bambang Suhendro, Ali Awaludin and Andreas Triwiyono

Published online: 25 January 2019

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chloride condition 01024

Teddy Tambunan, Mohd. Irwan Juki and Norzila Othman

Published online: 25 January 2019

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Doddy Prayogo

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Cross section and geometry optimization of steel truss arch bridges based on internal forces 02002

Malik Mushtofa, Akhmad Aminullah and Muslikh

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DOI: <https://doi.org/10.1051/mateconf/201925802002>

PDF (2.110 MB) | [References](#)

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Development of work breakdown structure (WBS) dictionary for the construction works of lower structure steel bridge 02003

Yusuf Latief, Dina Nurdiani and Leni Sagita Riantini Supriadi

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Informal housing construction workers' perceptions toward the improvement of effective leadership and performance 02004

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Identification of Stakeholders to Establishing Construction Safety Culture in Indonesia 02005

Yusuf Latief, Akhmad Suraji, Leni Sagita and Rossy Armyn Machfudiyanto

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Investigating Building Information Modelling (BIM) Adoption in Indonesia Construction Industry 02006

Jati Utomo Dwi Hatmoko, Yulian Fundra, Mochamad Agung Wibowo and Zhabrinna

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Jati Utomo Dwi Hatmoko, Bagus Hario Setiadji and Mohammad Agung Wibowo

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[Open Access](#)

Material quantity estimation modelling of bridge sub- structure using regression analysis 02008

M Khazin Alhusni, Andreas Triwiyono and Inggar Septhia Irawati

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PDF (1.857 MB) | [References](#)

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[Open Access](#)

Optimizing the prediction accuracy of load-settlement behavior of single pile using a self-learning data mining approach 02010

Doddy Prayogo and Yudas Tadeus Teddy Susanto

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DOI: <https://doi.org/10.1051/matecconf/201925802010>

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[Open Access](#)

Optimum seismic performance estimation of integrated multiple steel pipes bridge pier connected by shear panel damper with ANN method 02011

Angga S. Fajar and Akhmad Aminullah

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PDF (2.496 MB) | [References](#)

[Open Access](#)

Progressive Collapse Assessment: A review of the current energy-based Alternate Load Path (ALP) method 02012

Nur Ezzaryn Asnawi Subki, Hazrina Mansor, Yazmin Sahol Hamid and Gerard Parke

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Eryana Indah Kusumarukmi and Tri Joko Wahyu Adi

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PDF (1.328 MB) | [References](#)

(CEMA) 02014

Sarah Eden, Akhmad Aminullah and Andreas Triwiyono

Published online: 25 January 2019

DOI: <https://doi.org/10.1051/mateconf/201925802014>

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Järvenpää Esko and Quach Thanh Tung

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Peter F Kaming and Ogy Ade Yahya

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Debby Willar, Estrellita V. Y. Waney and Novatus Senduk

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The sustainability of human resource planning for construction projects 02018

Adegbenga Raphael Ashiru and Adebimpe Lucia Ashiru

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PDF (1.576 MB) | [References](#)

monitoring 02019

Lila Ayu Ratna Winanda, Achmad Arifin, Fauzan Arrofiqi, Trijoko Wahyu Adi and Nadjadji Anwar

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Agency cost estimation on flexible and rigid pavement 02020

Fajar Sri Handayani, Florentina Pungky Pramesti, Mochamad Agung Wibowo and Ary Setyawan

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Analysis of accident in Indonesian construction projects 02021

Toriq Ghuzdewan and Petrus Damanik

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Analysis Factors Affecting the Outcomes of Skilled Construction Workers Training in the Region of Central Sulawesi Province 02022

Nirmalawati, Mastura Labombang and Adnan Fadjar

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PDF (1.477 MB) | [References](#)

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Analysis of price fairness toward work quality and user satisfaction for architectural network 02023

Amalia N. Farini and Arief S.B. Nugroho

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DOI: <https://doi.org/10.1051/matecconf/201925802023>

PDF (1.730 MB) | [References](#)

Riza Yosia Sunindijo, Martin Loosemore, Fatma Lestari, Yuni Kusminanti, Baiduri Widanarko, Cynthia Febrina and Fiori Amelia

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DOI: <https://doi.org/10.1051/mateconf/201925802024>

PDF (1.611 MB) | [References](#)

Open Access

Computer-Integrated Manufacturing System for Membrane Structures 02025

Kazuo Yokobori and Tomo Miura

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DOI: <https://doi.org/10.1051/mateconf/201925802025>

PDF (2.078 MB) | [References](#)

Open Access

Construction project productivity assesment model and its implementation in Indonesia construction industry 02026

Rintih Prastianing Atas Kasih and Tri Joko Wahyu Adi

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DOI: <https://doi.org/10.1051/mateconf/201925802026>

PDF (2.028 MB) | [References](#)

Open Access

Cost prediction model based on system dynamics in water resource project 02027

Hirijanto, I Wayan Mundra and Addy Utomo

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DOI: <https://doi.org/10.1051/mateconf/201925802027>

PDF (1.612 MB) | [References](#)

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Johannes Tarigan, Andrew Pakpahan, Medis Surbakti and Nursyamsi Nursyamsi

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Open Access

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Torang Sitorus and Silvy Desharma

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PDF (1.869 MB) | [References](#)

Open Access

Analysis of building and its components condition assessment case study of dormitory buildings 03003

Sahaduta Linggar, Akhmad Aminullah and Andreas Triwiyono

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DOI: <https://doi.org/10.1051/mateconf/201925803003>

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Open Access

Apartment project risk assessment under market uncertainty; a case study in Wonokromo, Surabaya 03004

Aditya Sutantio, I Putu Artama Wiguna and Adi Tri Joko Wahyu

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DOI: <https://doi.org/10.1051/mateconf/201925803004>

PDF (1.868 MB) | [References](#)

Open Access

Application of 2D spatial imaging method for identification of a fault lines and subsurface landslide at "Taman Unnes", Semarang, Indonesia 03005

Lashari Lashari, Rini Kusumawardani, Togani Cahyadi Upomo, Supriyadi Supriyadi and Ajiwirani Mugiayulhaq

Published online: 25 January 2019

DOI: <https://doi.org/10.1051/mateconf/201925803005>

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[Open Access](#)

Assessment of Reinforced Concrete Building for Disaster Reduction Strategy in Padang City, West Sumatra, Indonesia 03007

Eka Juliafad and Annisa Prita Melinda

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DOI: <https://doi.org/10.1051/mateconf/201925803007>

PDF (2.068 MB) | [References](#)

[Open Access](#)

Evaluation of various GIS-based methods for the analysis of road traffic accident hotspot 03008

M. M. ZahranEl-Said, Tan Soon Jiann, Nurul Amirah 'Atiqah Binti Mohamad 'Asri Putra,

Eng Hie Angel Tan, Yok Hoe Yap and Ena Kartina Abdul Rahman

Published online: 25 January 2019

DOI: <https://doi.org/10.1051/mateconf/201925803008>

PDF (2.570 MB) | [References](#)

[Open Access](#)

Delamination mechanism of GFRP sheet bonded on the reinforced concrete beams 03009

Rudy Djamaluddin, Hijriah, Rita Irmawati, Faharuddin and Rossy T. Wahyuningsih

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DOI: <https://doi.org/10.1051/mateconf/201925803009>

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[Open Access](#)

Design Criterion of Reinforcement on Thick Soft Clay Foundations of Traditional Construction Method in Indonesia 03010

Suyuti Nurdin, Kazuhide Sawada and Shuji Moriguchi

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DOI: <https://doi.org/10.1051/mateconf/201925803010>

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Establishing factors of building vulnerability towards tsunami hazard 03011

Leli Honesti, Muhd Zaimi Abd Majid, Nazwar Djali and Meli Muchlian

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DOI: <https://doi.org/10.1051/mateconf/201925803011>

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Open Access

Evacuation egress in high rise building: Review of the current design evacuation solution 03012

Hazrina Mansor, Yazmin Sahol Hamid, Nurul Huda Suliman, Nursafarina Ahmad and Noorfaizah Hamzah

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Open Access

Experimental and numerical investigations on overall buckling of steel pipe truss with circular cutout on the compression element 03013

Miftahul Iman, Bambang Suhendro, Henricus Priyosulistyo and Muslikh

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DOI: <https://doi.org/10.1051/mateconf/201925803013>

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Flood-induced Bridge Failures in Papua New Guinea 03014

Gibson Ali Holemba and Takashi Matsumoto

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[PDF \(2.165 MB\)](#) | [References](#)

Open Access

Investigating the Mechanism of Shear Fatigue in Reinforced Concrete Beams subjected to Pulsating and Moving Loads using Digital Image Correlation 03015

Benny Suryanto, George Staniforth, Jaehwan Kim, Esayas Gebreyouhannes, Nobuhiro Chijiwa, Chikako Fujiyama and Peter K. Woodward

Open Access

Modelling the performance of a corroded pipe section repaired with three-parts epoxy grout and with three-parts epoxy grout plus nanofiller 03016

Siti Norasyikin Hj Kariya and Pang Jen Lim

Published online: 25 January 2019

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[PDF \(1.665 MB\)](#) | [References](#)

Open Access

Prediction analysis of the degradation and the service life building components in artificial method neural network and ISO factor 15686-2 03017

Siti Aisyah, Akhmad Aminullah and H. Muslikh

Published online: 25 January 2019

DOI: <https://doi.org/10.1051/mateconf/201925803017>

[PDF \(1.743 MB\)](#) | [References](#)

Open Access

Seismic Performance Evaluation of a Multistory RC Building in Padang City 03018

Jafril Tanjung, Maidiawati and Fajar Nugroho

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DOI: <https://doi.org/10.1051/mateconf/201925803018>

[PDF \(2.226 MB\)](#) | [References](#)

Open Access

Study of Pavement Condition Index (PCI) relationship with International Roughness Index (IRI) on Flexible Pavement. 03019

Rijal Psalmen Hasibuan and Medis Sejahtera Surbakti

Published online: 25 January 2019

DOI: <https://doi.org/10.1051/mateconf/201925803019>

[PDF \(1.903 MB\)](#) | [References](#)

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the-art review 05017

Seplika Yadi, Bambang Suhendro, Henricus Priyosulistyo and Akhmad Aminullah

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Aiko Ikeda, Kai Hashimoto, Teeranai Srimahachota, Hao Zheng and Shunji Kanie

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Yasuhiro Koda, Shohei Minakawa and Ichiro Iwaki

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Yuko Yasuda, Ko Kakuma, Yoshitaka Shiroto and Takashi Matsumoto

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Mahmud Kori Effendi and Nor Hayati Abdul Hamid

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Numerical study of inelastic buckling behavior of rectangular steel plates with circular openings under shear forces 05026

Rajawali M Akbar and Bambang Suryoatmono

Open Access

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Widodo Pawirodikromo

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Performance of an existing reinforced concrete building designed in accordance to older Indonesian codes (pptgiug 1983 and sksni t-15-1991-03): case study for a hotel in Balikpapan 05028

Pamuda Pudjisuryadi, Elian Davin Mulyadi, Ferry and Benjamin Lumantarna

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Structural analysis using three-component acceleration time histories caused by shallow crustal fault earthquakes with a maximum magnitude of 7 Mw 05029

Windu Partono, Yulita Ami Priastivi, Nuroji, Indrastono Dwi Atmanto, Bambang Pardoyo, Trinita Octaviani Gultom and Yanuar Tampubolon

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Gogot Setyo Budi, Hurijanto Koentjoro, Joshua Wijaya and Evan Filbert Sikomena

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Arie Wardhono

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Shams Shahriar, Zahran El-Said M. M., Said Safwanah N. M., Hui Kho J., Naderah N. D. H. M. F. Lee and N. H. H. Hasim

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Naomi Pratiwi and Paulus Karta Wijaya

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Review of creep modelling for predicting of long-term behavior of glued-laminated bamboo structures

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Abstract. Glued-laminated bamboo has been widely used to substitute timber as a building material. This material classified as a viscoelastic material because it exhibiting properties that are common to both solid and liquid. Under long-term constant loading, the glued-laminated bamboo structures will experience creep deformation. The mechanical, power law and finite element models are common methods that used to predict the creep for viscoelastic material, some of them have advantages and disadvantages. In this manuscript, modelling of long-term creep is reviewed. The fundamental concepts of creep modelling, the influence of variable load level, and humidity were discussed to develop for computational applications. By using FEA program, a subroutine has been developed by previous researchers to accommodate the effect of orthotropic properties. In the future, the subroutine will be used and developed for numerical creep analysis of glued-laminated bamboo.

Keywords: long-term behavior, creep, creep modelling, glued-laminated bamboo

1 Introduction

Glued-laminated bamboo has been widely used to substitute timber as a building material is a natural resource with many benefits. Because the glued-laminated bamboo produced from bamboo the benefits including, for example, environmentally friendly, renewable and sustainable material, good mechanical properties and similar with timber [1-3]. Glued-laminated bamboo is classified as a viscoelastic material because it exhibits properties that are common to both solid and liquid. Under long-term constant loading, the glued-laminated bamboo will be causing creep. The phenomenon of creep, especially in anisotropic or orthotropic materials is critical to structural design. For instance, creep on beams will cause P - Δ effects, can possibly influence the serviceability of structures. Another problem due to creep is the ability to alter the material characteristics and mechanical properties of the structural elements, furthermore, will cause failure of a building structure [4-5]

There are many ways to predict the creep for viscoelastic material, some of them, including mechanical, power law and finite element model are common methods. In this manuscript, modelling of long-term creep is reviewed, and the fundamental concepts of creep modelling, the influence of variable load level, temperature and humidity will be discussed to develop for computational applications. By using finite element analysis (FEA) program, a subroutine has been developed by previous researchers to accommodate the effect of orthotropic properties. In the future, the subroutine will be used and developed for numerical creep analysis of glued-laminated bamboo.

2 Viscoelastic Constitutive Equations

The long-term deformation behavior of a material can be approximated by a linear viscoelastic theory. According to Hook's law, the constitutive equation of linear viscoelastic material is a function of time, written in matrix form in equation (1). The independent components matrix could be determined experimentally, by using uniaxial (compression, tension, shear) creep tests.

$$\{\varepsilon(t)\} = [D(t)]\{\sigma\} \quad (1)$$

For linear viscoelastic orthotropic material,

$$\begin{Bmatrix} \varepsilon_x(t) \\ \varepsilon_y(t) \\ \varepsilon_z(t) \\ \gamma_{xy}(t) \\ \gamma_{xz}(t) \\ \gamma_{yz}(t) \end{Bmatrix} = \begin{bmatrix} \frac{1}{E_1(t)} & -\frac{\nu_{21}}{E_2(t)} & -\frac{\nu_{31}}{E_3(t)} & 0 & 0 & 0 \\ -\frac{\nu_{12}}{E_1(t)} & \frac{1}{E_2(t)} & -\frac{\nu_{32}}{E_3(t)} & 0 & 0 & 0 \\ -\frac{\nu_{13}}{E_1(t)} & -\frac{\nu_{23}}{E_2(t)} & \frac{1}{E_3(t)} & 0 & 0 & 0 \\ 0 & 0 & 0 & \frac{1}{2G_{23}(t)} & 0 & 0 \\ 0 & 0 & 0 & 0 & \frac{1}{2G_{13}(t)} & 0 \\ 0 & 0 & 0 & 0 & 0 & \frac{1}{2G_{12}(t)} \end{bmatrix} \begin{Bmatrix} \sigma_x \\ \sigma_y \\ \sigma_z \\ \tau_{xy} \\ \tau_{xz} \\ \tau_{yz} \end{Bmatrix}$$

For linear viscoelastic isotropic material,

$$\begin{Bmatrix} \varepsilon_x(t) \\ \varepsilon_y(t) \\ \varepsilon_z(t) \\ \gamma_{xy}(t) \\ \gamma_{xz}(t) \\ \gamma_{yz}(t) \end{Bmatrix} = \frac{1}{E(t)} \begin{bmatrix} 1 & -\nu & -\nu & 0 & 0 & 0 \\ -\nu & 1 & -\nu & 0 & 0 & 0 \\ -\nu & -\nu & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 2(1+\nu) & 0 & 0 \\ 0 & 0 & 0 & 0 & 2(1+\nu) & 0 \\ 0 & 0 & 0 & 0 & 0 & 2(1+\nu) \end{bmatrix} \begin{Bmatrix} \sigma_x \\ \sigma_y \\ \sigma_z \\ \tau_{xy} \\ \tau_{xz} \\ \tau_{yz} \end{Bmatrix}$$

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3 Rheological Model

In the rheological model, glued-laminated bamboo is assumed to behave as a viscoelastic material. In general, there are two forms used to represent the stress-strain-time relationship of viscoelastic materials. They are known as the differential operator (mechanical model) and the integral representation (Boltzmann Superposition Principle Model). The differential operator model has been widely used for analysis since the mathematical processes required are reasonably simple. While, the integral representation is able to describe the time dependence more generally, however, it sometimes leads to difficult mathematics in stress analysis [6].

3.1. Mechanical Model

A mechanical model can be used to visualize the stress-strain relationship of the viscoelastic material due to the constant applied load within a certain time. In this model using linear elastic spring (**Fig. 1 (a)**) to idealize linear elastic solid and linear viscous dashpot (**Fig. 1 (b)**) to idealize viscous fluid. The constitutive equations in linear elastic solid and viscous fluid are shown in equation (2) and (3)

$$\varepsilon = \frac{\sigma}{E}; \tag{2}$$

$$\dot{\varepsilon} = \frac{\sigma}{\eta} \tag{3}$$

where ε : strain; σ : applied stress; E : Young Modulus; $\dot{\varepsilon}$: rate of strain; η : viscosity; t : time



Fig. 1. (a) Linear elastic spring; (b) Linear dashpot [6]

Generally, the constitutive equation of viscoelastic linear material is presented in the form of the following differential equation [6]

$$p_0\sigma + p_1\dot{\sigma} + p_2\ddot{\sigma} + \dots + p_n \frac{\partial^n \sigma}{\partial t^n} = q_0\varepsilon + q_1\dot{\varepsilon} + q_2\ddot{\varepsilon} + \dots + q_n \frac{\partial^n \varepsilon}{\partial t^n} \tag{4}$$

where p_0, p_1, p_2, \dots and q_0, q_1, q_2, \dots are material constants, this constitutive equation of linear function to stress (σ), strain (ε) and derivative with time $\dot{\sigma}, \ddot{\sigma}, \dots$ and $\dot{\varepsilon}, \ddot{\varepsilon}, \dots$

There are several variations of the constitutive equation of viscoelastic linear material depending on combination number of the spring and the dashpot elements. For example, Maxwell and Kelvin model are adequate for qualitative and conceptual analysis, but generally poor

for the quantitative representation of the behavior real materials. In order to improve the representation, a user needs to increase the number of elements by combining a number of springs and dashpots.

The simplest linear model that successfully describes the time-dependent behavior of viscoelastic material such as timber, bamboo, glued-laminated bamboo, etc, under constant humidity and temperature for a short period are four-element model or Burger model illustrated in **Fig. 2**, where the Maxwell and Kelvin model are connected in series. The constitutive equation can be derived by considering the strain response under constant applied loading. The total strain at the time it is obtained by summing the strain on four elements is given by the equation (5), where ε : strain at time t , σ_0 : constant applied load, E_M : elasticity of element spring Maxwell, E_K : elasticity of element spring Kelvin, η_M : viscosity of element dashpot Maxwell, η_K : viscosity of element dashpot Kelvin. The first term on the right-hand side of the equation (5) represents instantaneous deformation, the second term describes delayed elasticity and the third term plastic flow component. So, the first term describes the elastic behavior while the combination of the second and third terms accounts for the viscoelastic or creep behavior. It should be noticed that the Burger model is valid only for primary and secondary creep behavior. The typical creep and relaxation of Burger model shown in **Fig. 3**.

$$\varepsilon(t) = \frac{\sigma_0}{E_M} + \frac{\sigma_0}{\eta_M} t + \frac{\sigma_0}{E_K} (1 - e^{-(E_K / \eta_K)t}) \tag{5}$$

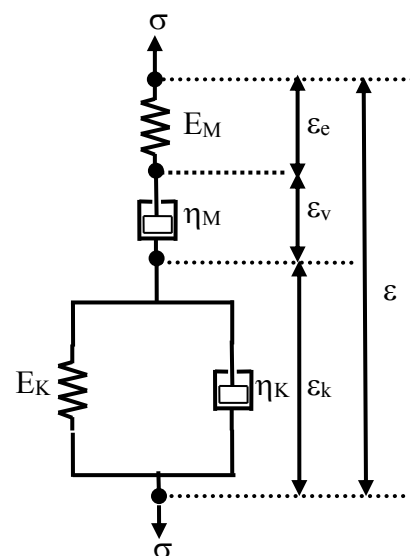


Fig. 2. Burger Model [6]

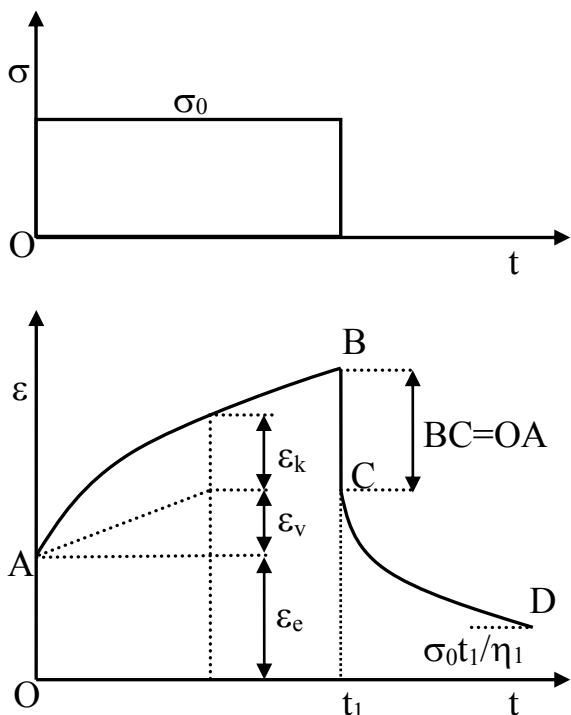


Fig. 3. Typical creep and Relaxation Burger Model [6]

For accommodate the effect of humidity conditions that often called mechano-sorptive, Leicester [7] proposed a rheological model for mechano-sorptive creep in wood beams during drying. In this model was a modified Maxwell model, where the dashpot element had been substituted by a mechano-sorptive creep element shown in Fig. 4.

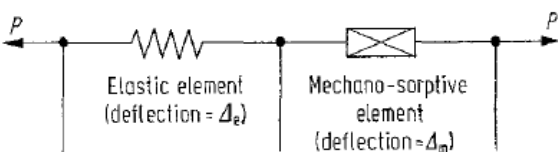


Fig. 4. The mechanical model for mechano-sorptive effect [7]

According to Fig 4, total deflection Δ of a wood beam was assumed to be the sum of an elastic component Δ_e and a mechano-sorptive component Δ_m as follows.

$$\Delta = \Delta_e + \Delta_m \quad (6)$$

$$\Delta_e = KP \quad (7)$$

$$-\frac{d\Delta_m}{dm} = P \cdot f(m) \quad (8)$$

where P : load parameter, K : constanta, m : moisture content and $f(m)$: a function of moisture content. Ranta-Maunus [8] developed a generalized viscoelastic model for wood that includes moisture changes. In the one dimensional (1D) case the constitutive equation may then be written in the form

$$\begin{aligned} \varepsilon(t) = & \int_0^t J(t-\tau)d\sigma(\tau) \\ & + \int_0^t [K(t-\tau)\sigma(t) + L(t-\tau)(\sigma(t) - \sigma(\tau))(u(t) - u(\tau))] du(\tau) \end{aligned} \quad (9)$$

where ε : strain, σ : stress, u : moisture content, J : viscoelastic compliance, K , and L are kernel functions describing the mechano-sorptive creep behavior and t and τ are time variables. In Equation (9), the material is assumed to be reduced to time $t = 0$. Different values of K during absorption and desorption are important to describe mechano-sorptive creep.

Fridley et al. [9] had been modified four element model (Burger model), where a mechano-sorptive element is added to this model to account for observed mechano-sorptive strain (Fig. 5).

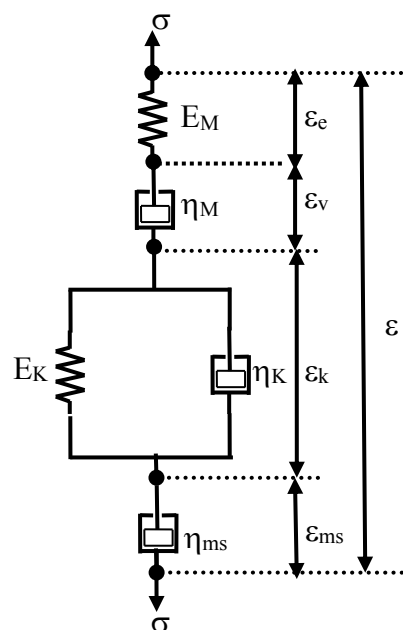


Fig. 5. Modified Burger Model with Mechano-sorptive Element [9]

The mechano-sorptive element is assumed to have a viscous parameter defined as a function rate of change moisture content as follows:

$$\eta_{ms} = \frac{\eta'_{ms}}{|\dot{\omega}|} \quad (10)$$

where η_{ms} : viscosity of the mechano-sorptive element; η'_{ms} : constanta with units force per unit area; and $\dot{\omega}$: rate of change moisture content. The rate of mechano-sorptive strain ($\dot{\varepsilon}_{ms}$) defined as

$$\dot{\varepsilon}_{ms} = \frac{\sigma}{\eta_{ms}} \quad (11)$$

If the average moisture content of the specimen after a sudden change in the surrounding environment is assumed

$$\omega(t_\omega) = \omega_e + (\omega_i - \omega_e) \exp(-B_\omega t_\omega) \quad (12)$$

The derivative of equation (12) to time is

$$\dot{\omega}(t_\omega) = B_\omega (\omega_e - \omega_i) \exp(-B_\omega t_\omega) \quad (13)$$

where $\omega(t_0)$: average moisture content at a time t_0 following the environmental change; ω_e : equilibrium moisture content in a new environment; ω_i : initial moisture content in the original environment; and B_{ω} : constant associated with the time required to achieve moisture equilibrium. The value of the B_{ω} is determined from curve fitting the relationship between time and moisture content, as an exponential function. For a constant applied load and changing moisture condition, the total mechano-sorptive strain is :

$$\varepsilon_{ms} = \frac{\sigma}{\mu_{ms}} \left[\Delta\omega \left\{ 1 - \exp(-B_{\omega} t_{\omega}) \right\} \right] \quad (14)$$

where, $\Delta\omega = \omega_e - \omega_i$; η'_{ms} mechano-sorptive constant can be estimated using an iterative best-fit procedure from experimental data. So, the total strain of material when subjected to constant applied load and moisture content variation at a time t is,

$$\varepsilon(t) = \varepsilon_e + \varepsilon_k + \varepsilon_{ms} \quad (15)$$

3.2. Boltzmann Superposition Principle Model

Boltzmann Superposition Principle Model or commonly referred to as integral representation can explain the relationship of stress-strain that is affected by time. The advantage of using this method is that it can be used more flexibly to model creep resulting from a constant step loading. If on a creep test, a gradual load is given where σ_0 is given for ζ_1 , then the load is increased by σ_1 for ζ_2 and so on (Fig. 6), then $\varepsilon(t)$ can be determined by equation (16).

$$\varepsilon(t) = \sum \varepsilon(\sigma_0, \xi_1) + \varepsilon(\Delta\sigma_1, \xi_2) + \dots + \varepsilon(\Delta\sigma_i, \xi_i) \quad (16)$$

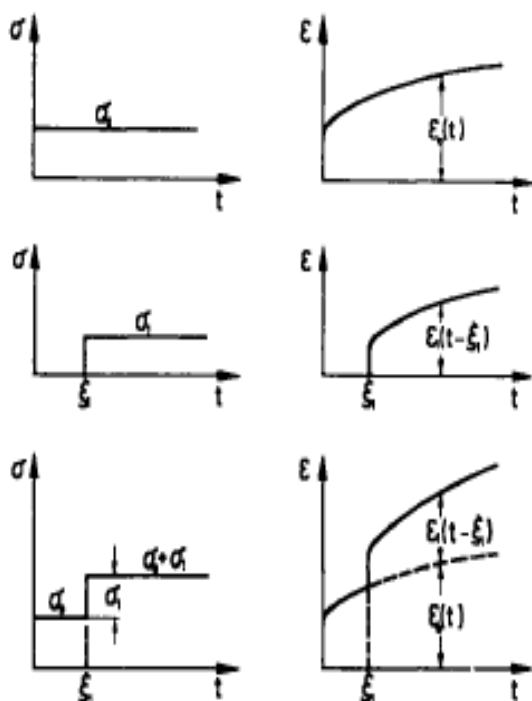


Fig. 6. Boltzmann Superposition Principle Model [6]

4 Power Law Model

Modelling the time-dependent behavior of glued-laminated bamboo can be expressed empirical mathematical equations. One of the most successfully descriptions for creep in the viscoelastic material under constant relative humidity and temperature is the power law model, of the general form [6,10]

$$\varepsilon(t) = \varepsilon_0 + at^m \quad (17)$$

where $\varepsilon(t)$: time-dependent strain, ε_0 : instantaneous strain, a and m are material constants can be determined with curve fitting experiment data, and t : elapsed time. The empirical equation above can adequate to describe a secondary stage, nonlinear creep behavior of the viscoelastic material, and easier than using other models.

5 Finite Element Model

Because of mathematical difficulties, few real problems in viscoelasticity have an analytical solution. As in many other areas of science, the use of numerical analyses and digital computers had a great impact in this field. Procedures based on techniques like Finite Element can provide analysis for structures made of linear and nonlinear viscoelastic materials. In part, these numerical procedures by using FEA program ABAQUS are described.

Modelling creep behavior of viscoelastic linear material on the FEA program ABAQUS, can be modeled as a prony series elements Maxwell models, plus a single elastic element G_{∞} (Fig. 7).

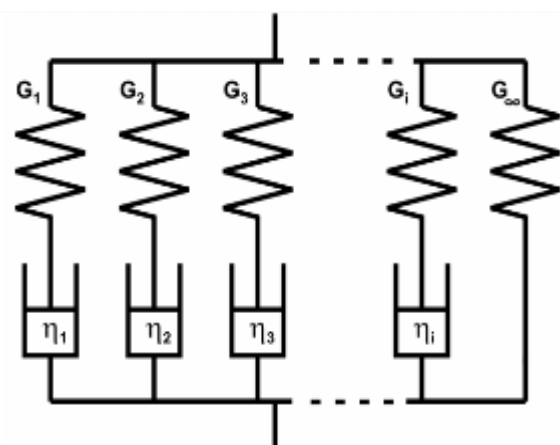


Fig. 7. Prony Series Elements Maxwell Model [11]

In the FEA program ABAQUS the prony series can be written with shear modulus (G) as follows:

$$G(t) = G_{\infty} + \left(\sum_{i=1}^n g_i G_0 e^{(-t/\tau_i)} \right) \quad (18)$$

where

t: time, $\tau_i = \eta_i / E_i$: relaxation time, $G_0 = \frac{E}{2(1+\nu)}$;

initial shear modulus, $g_i = G_i / G_0$, at $t = 0$,

$G_\infty = G_0(1 - \sum_{i=1}^n g_i)$ so the prony series can be

written:

$$G(t) = G_0 \left(1 - \sum_{i=1}^n g_i \right) + \left(\sum_{i=1}^n g_i G_0 e^{(-t/\tau_i)} \right) \quad (19)$$

Kon and Yuan [12]; Ngudiyono et al. [3] by using Laplace Transformation method for converting the Burger Model to Prony Series in FEA program ABAQUS as follows

$$G(t) = G_\infty + \left(\sum_{i=1}^n G_i G_0 e^{(-t/\tau_i)} \right) \quad (20)$$

If $n = 2$ so,

$$G(t) = G_\infty + G_1 e^{(-t/\tau_1)} + G_2 e^{(-t/\tau_2)} \quad (21)$$

where,

$$G_\infty = 0, G_1 = \frac{G_M}{(\alpha - \beta)} \left(\frac{G_K}{\eta'_K} - \beta \right),$$

$$G_2 = \frac{G_M}{(\alpha - \beta)} \left(\alpha - \frac{G_K}{\eta'_K} \right), \tau_1 = \frac{1}{\beta}, \tau_2 = \frac{1}{\alpha}$$

If

$$g(t) = \frac{G(t)}{G_0}$$

$$G(t) = G_\infty + G_0 (g_1 e^{(-t/\tau_1)} + g_2 e^{(-t/\tau_2)}) \quad (22)$$

where

$$G_0 = G_M, g_1 = \frac{1}{(\alpha - \beta)} \left(\frac{G_K}{\eta'_K} - \beta \right), g_2 = \frac{1}{(\alpha - \beta)} \left(\alpha - \frac{G_K}{\eta'_K} \right)$$

$E_M, \mu_M, g_1, g_2, \tau_1, \tau_2$ is a Burger model parameter that can be used in the FEA program ABAQUS.

The behavior of the viscoelastic material in FEA program ABAQUS can also be modeled using the power law function which involves two variables, i.e., constant applied load (σ) and time (t). The power law approach is more effective than the classical mathematical approach (such as Maxwell, Kelvin, Burger, and others). The power law function is appropriate to explain nonlinear behavior. The power law equation is expressed in the rate of creep ($\dot{\epsilon}_{cr}$) as follows,

$$\dot{\epsilon}_{cr} = A \sigma^n t^m \quad (23)$$

If equation (23) is integrated with time (t), then the creep strain (ϵ_{cr}) is,

$$\epsilon_{cr} = \frac{A}{m+1} \sigma^n t^{m+1} \quad (24)$$

where A, n , and m creep parameters can be obtained from the curve fitting of the creep test experimental data. In FEA program ABAQUS the value of A and n is

greater than 0 ($A, n > 0$) while the m value is more than -1 and less than or equal to 0 ($-1 < m \leq 0$).

For the creep model of anisotropic or orthotropic material, the potential option is used to define the anisotropic or orthotropic stress creep ratio $R_{11}, R_{22}, R_{33}, R_{12}, R_{13}, R_{23}$ where:

$$R_{11} = \frac{\sigma_{11}}{\tilde{q}}, R_{22} = \frac{\sigma_{22}}{\tilde{q}}, R_{33} = \frac{\sigma_{33}}{\tilde{q}},$$

$$R_{12} = \frac{\sigma_{12}}{\tilde{q}/\sqrt{3}}, R_{13} = \frac{\sigma_{13}}{\tilde{q}/\sqrt{3}}, R_{23} = \frac{\sigma_{23}}{\tilde{q}/\sqrt{3}}$$

\tilde{q} = Hill's stress equivalent

If the constitutive models are not available in the FEA program, the user is given the opportunity to add a constitutive model by creating subroutines. UMAT and DFLUX are subroutines to define a constitutive model of viscoelastic material for predicting creep behavior.

Mirianon et al. [13] had been using a viscoelastic and mechano-sorptive subroutine for time-dependent analysis that implemented into the user subroutine UMAT and DFLUX to define the rheological model and the flow of moisture on the surface of the wood. In this model is characterized by five deformation mechanisms (Fig. 8) which provide an additive decomposition of the strain. The time-dependent analysis can be solved by using an incremental analysis in time which takes into account the coupling of moisture changes and stresses. At the time $t = t_n$ the solution in terms of strain, stress, and moisture is assumed to be known, while solution at the time $t = t_{n+1}$ is determined. The total strain can be considered as composed of several parts which are related to different mechanisms acting in series:

$$\epsilon = \epsilon^e + \epsilon^u + \epsilon^{ve} + \epsilon^{ms} + \epsilon^{ms(irr)} \quad (25)$$

where ϵ : total strain, ϵ^e : elastic strain, ϵ^u : hygroexpansion strain, ϵ^{ve} : total viscoelastic strain, ϵ^{ms} : recoverable mechano-sorptive strain, and $\epsilon^{ms(irr)}$: irrecoverable mechanosorptive strain. Equation (25) can be rewritten in terms of finite increments as follows:

$$\Delta \epsilon^e + \Delta \epsilon^{ve} + \Delta \epsilon^{ms} = \Delta \epsilon - \Delta \epsilon^u - \Delta \epsilon^{ms(irr)} \quad (26)$$

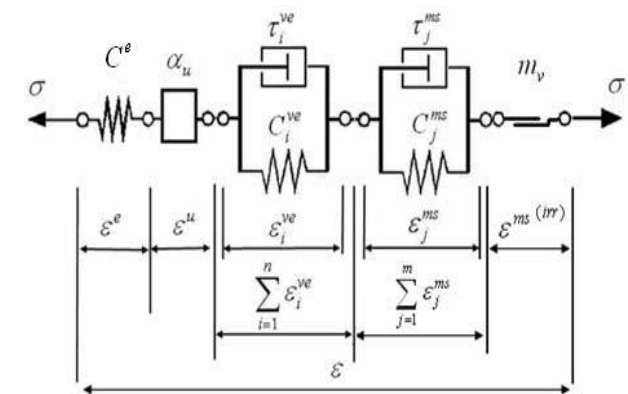


Fig. 8. Scheme 3D of the rheological model [13]

5 Modelling of Glued-Laminated Bamboo Structures with FEA Program ABAQUS

Li and Xiao [14] had been used Burger model for compression and tensile one dimension (1D) creep analysis of glued-laminated bamboo, without considering the effect of humidity condition and orthotropic properties material. Currently, there is no ready-made glued-laminated bamboo model in FEA program ABAQUS for time-dependent analysis, but there are ways to create your own material models using subroutines. In the present study, it is necessary to use the UMAT and DFLUX subroutine to define the rheological model and the flow of moisture on the surface of the glued-laminated bamboo. UMAT calculates the stress increment and the Jacobian matrix for each time increment. DFLUX calculates the flow of moisture between air and glued-laminated bamboo surfaces. The following scheme (Fig. 9) describes the modelling and calculating processes used for modelling glued-laminated bamboo.

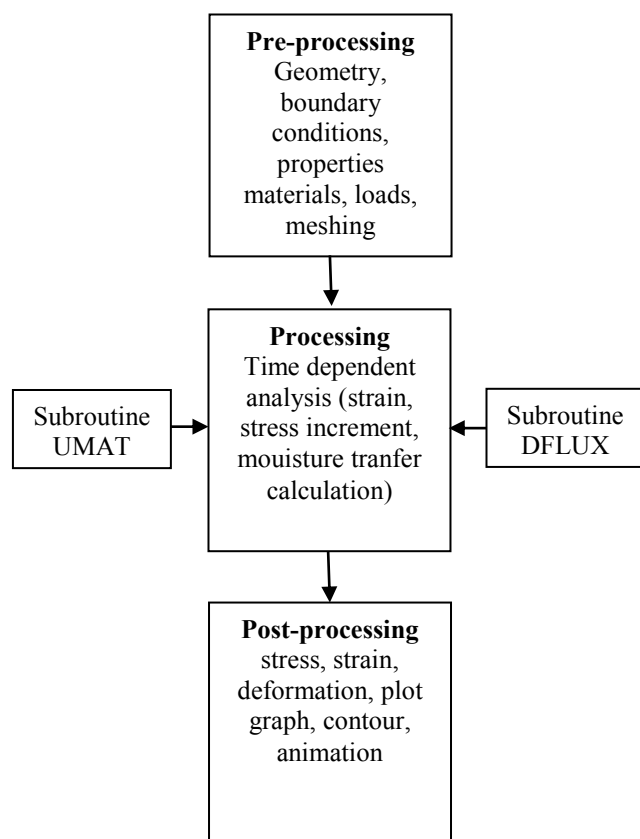


Fig. 9. Scheme modelling glued-laminated bamboo with FEA Program ABAQUS

6 Conclusions

There are several models to model creep behavior viscoelastic material. The differential operator (mechanical model, i.e., Maxwell, Kelvin, Burger model), the integral representation (Boltzmann Superposition Principle Model), Power Law and Finite Element Model. Modified mechanical models (Maxwell, Burger model) by adding mechano-shortive elements can be used to predict creep behavior of viscoelastic materials such as glued-laminated bamboo due to the variable relative humidity effects. The power law approach is more effective than the classical mathematical approach (such as Maxwell, Kelvin, Burger, and others) and can describe nonlinear creep behavior viscoelastic material. The time-dependent analysis model for the long-term behavior of glued-laminated bamboo under constant loading and moisture variables can be developed with finite element models using FEA program ABAQUS. The rheological model is implemented with the UMAT subroutine, and moisture transfer is implemented in the DFLUX subroutine.

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